

# Multifunctional rotary actuator for 2 and 3 way control ball valves

- Torque 5 Nm
- Nominal voltage AC/DC 24 V
- Control: Modulating DC 0 ... 10 V or variable
- Position feedback DC 2 ... 10 V or variable
- · Communication via BELIMO MP-Bus
- · Conversion of sensor signals



Nominal voltage	Technical data					
Power supply range         AC 19.2 28.8 V / DC 21.6 28.8 V           Power consumption in operation At rest At 1.2 W For wire sizing         2 W at nominal torque (above 1.2 W)           Connection         Cable 1 m, 4 x 0.75 mm²           Functional data         Factory settings         Variable         Settings           Torque (nominal torque)         Min. 5 Nm at nominal voltage         Open-close, 3-point (AC only)         Start point DC 25 30 V End point DC 25 30 V End point DC 25 30 V End point DC 25 32 V           Position feedback (measuring voltage U)         DC 2 10 V, max. 0.5 mA         Start point DC 0.5 8 V End point DC 2.5 32 V           Position feedback (measuring voltage U)         DC 2 10 V, max. 0.5 mA         Start point DC 0.5 8 V End point DC 2.5 10 V           Uni-rotation         ±5% absolutely         *** *** *** *** *** *** *** *** *** **	Electrical data					
Power consumption In operation At rest 1.2 W 1.2 W 3.5 VA  Connection Cable 1 m, 4 x 0.75 mm²  Functional data Factory settings Variable Settings  Torque (nominal torque) Min. 5 Nm at nominal voltage  Control Control Signal Y DC 0 10 V, input impedance 100 kΩ Start point DC 0.5 30 V End point DC 2.5 32 V Position feedback (measuring voltage U)  Uni-rotation ±5% absolutely  Running time 99 s 99 °- 3 S5 150 s Automatic adaption whenever the supply voltage is switched on, or menual triggering of this adaption by pressing the button -Adaption- or with the PC-Tool MIN (minimum position) = 100% MIN = 0% (MAX - 30°-4) z S6 (MAX - 30°-4) z S7 (MAX - 30°-4)	Nominal voltage	AC 24 V, 50/60 Hz / DC 24 V				
At rest   1.2 W   South   S	Power supply range	AC 19.2 28.8 V / DC 21.6 28.8 V				
Source	Power consumption In operation	2 W at nominal torque				
Functional data   Factory settings   Variable   Settings	At rest	1.2 W	·			
Functional data Pactory settings  Variable Settings  Torque (nominal torque)  Min. 5 Nm at nominal voltage Control Control signal Y Working range  DC 2 10 V DC 2 10 V Position feedback (measuring voltage U)  Uni-rotation  ### ### ### ### ### ### ### ### ### #	For wire sizing	3.5 VA				
Torque (nominal torque)  Control Control signal Y Working range  DC 0 10 V, input impedance 100 kΩ Start point DC 0.5 30 V End point DC 0.5 32 V  Position feedback (measuring voltage U)  Uni-rotation  ±5% absolutely  Running time 90 s/90° -□ Automatic adjustment of running time, operating range and measuring signal U breath the mechanical angle of rotation  Angle de rotation limiting  MaX (maximum position) = 0% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN (minimum position) = 0% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30 · □) 100% MIN = 0% (MAX - 30	Connection	Cable 1 m, 4 x 0.75 mm <sup>2</sup>				
Control Control signal Y Working range       DC 0 10 V, input impedance 100 kΩ Pc 2 10 V       Open-close, 3-point (AC only) Start point DC 0.5 30 V End point DC 2.5 32 V         Position feedback (measuring voltage U)       DC 2 10 V, max. 0.5 mA       Start point DC 0.5 8 V End point DC 0.5 8 V End point DC 0.5 8 V         Uni-rotation       ±5% absolutely         Running time       90 s/90 °<√	Functional data	Factory settings	Variable	Settings		
Working range   DC 2 10 V   Start point   DC 0.5 30 V   End point   DC 2.5 32 V   DC 2.		<u> </u>				
Position feedback (measuring voltage U)	Control Control signal Y	DC 0 10 V, input impedance 100 k $\Omega$	Open-close, 3-point (AC only)			
Uni-rotation	Working range	DC 2 10 V				
Running time       90 s/90 ° ¬ ∃       35 150 s         Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation       Manual triggering of this adaption by pressing the button «Adaption» or with the supply voltage is switched on, or manual triggering         Angle de rotation limiting       MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% ZS = MIN MAX = 0.00 ¬ √ √ √ √ √ √ √ √ √ √ √ √ √ √ √ √ √ √	Position feedback (measuring voltage U)	DC 2 10 V, max. 0.5 mA				
Automatic adjustment of running time, operating range and measuring signal U to match the mechanical angle of rotation the PC-Tool  Angle de rotation limiting  MAX (maximum position) = 100% MIN (minimum position) = 0% MIN = 0% (MAX − 30° ≺1) 100% MIN (minimum position) = 50% MIN = 0% (MAX − 30° √1) 100% MIN (minimum position) = 50% MIN = 0% (MAX − 30° √1) 100% MIN = 0% (MAX − 30° √1) 100% MIN (minimum position) = 50% MIN = 0% (MAX − 30° √1) 100% MIN = 0% 45 B B B B B B B B B B B B B B B B B B	Uni-rotation	±5% absolutely				
operating range and measuring signal U to match the mechanical angle of rotation the PC-Tool on, or manual triggering on, or manual triggering.  Mil Safety extra-low only) of Mil N (Miln a running 35 s = 45 dB (A) (Mil N or MAX = (MIN + 30 °C) or Mil N or or or or what a running 35 s = 45 dB (A) (Mil N or or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mi	Running time	90 s/90° <i>⊲</i>	35 150 s			
operating range and measuring signal U to match the mechanical angle of rotation the PC-Tool on, or manual triggering on, or manual triggering.  Mil Safety extra-low only) of Mil N (Miln a running 35 s = 45 dB (A) (Mil N or MAX = (MIN + 30 °C) or Mil N or or or or what a running 35 s = 45 dB (A) (Mil N or or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mil N or or or whith a running 35 s = 45 dB (A) (Mi	Automatic adjustment of running time,	Manual triggering of this adaption by	Automatic adaption whenever			
Angle de rotation limiting  MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% MIN = 0% (MAX - 30°¬¬) 100% MIN = 0% (MAX - 30°¬¬¬) 100% MIN = 0% (MAX - 30°¬¬¬¬) 100% MIN = 0% (MAX - 30°¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬¬	operating range and measuring signal U		the supply voltage is switched			
MIN (minimum position) = 0% MIN = 0% (MAX − 30° ≺) ZS (intermediate position, AC only) = 50% ZS = MIN MAX  Sound power level Max. 35 dB (A) With a running 35 s = 45 dB (A) time of 90 s = 35 dB (A)  Position indication Mechanical, plug-on  Safety  Protection class III Safety extra-low voltage  Degree of protection IP54 in all mounting positions  EMC CE according to 89/336/EEC  Mode of operation Type 1 (to EN 60730-1)  Rated impulse voltage 0.8 kV (to EN 60730-1)  Control pollution degree 3 (in acc. with EN 60730-1)  Ambient temperature range +0 +50°C  Temperature of medium +5 +110°C in control ball valve −10°C with stem heating upon request  Non-operating temperature -40 +80°C  Ambient humidity range 95% r.H., non-condensating (to EN 60730-1)  Maintenance Maintenance-free  Dimensions See «Dimensions» on page 5	to match the mechanical angle of rotation	the PC-Tool	on, or manual triggering			
ZS (intermediate position, AC only) = 50% ZS = MIN MAX  Sound power level  Max. 35 dB (A)  With a running 35 s = 45 dB (A) time of 90 s = 35 dB (A)  Position indication  Mechanical, plug-on  Safety  Protection class  III Safety extra-low voltage  Degree of protection  IP54 in all mounting positions  EMC  CE according to 89/336/EEC  Mode of operation  Type 1 (to EN 60730-1)  Rated impulse voltage  0.8 kV (to EN 60730-1)  Control pollution degree  3 (in acc. with EN 60730-1)  Ambient temperature range  +0 +50°C  Temperature of medium  +5 +110°C in control ball valve -10°C with stem heating upon request  Non-operating temperature  -40 +80°C  Ambient humidity range  95% r.H., non-condensating (to EN 60730-1)  Maintenance  Maintenance-free  Dimensions  See «Dimensions» on page 5	Angle de rotation limiting	MAX (maximum position) = 100%	MAX = (MIN + 30°<) 100%			
Sound power level  Max. 35 dB (A)  With a running 35 s = 45 dB (A) time of 90 s = 35 dB (A)  Position indication  Mechanical, plug-on  Safety  Protection class  III Safety extra-low voltage  Degree of protection  IP54 in all mounting positions  EMC  CE according to 89/336/EEC  Mode of operation  Type 1 (to EN 60730-1)  Rated impulse voltage  0.8 kV (to EN 60730-1)  Control pollution degree  3 (in acc. with EN 60730-1)  Ambient temperature range  +0 +50°C  Temperature of medium  +5 +110°C in control ball valve  -10°C with stem heating upon request  Non-operating temperature  -40 +80°C  Ambient humidity range  95% r.H., non-condensating (to EN 60730-1)  Maintenance  Dimensions/weight  Dimensions  See «Dimensions» on page 5						
Position indication Mechanical, plug-on  Safety  Protection class III Safety extra-low voltage  Degree of protection IP54 in all mounting positions  EMC CE according to 89/336/EEC  Mode of operation Type 1 (to EN 60730-1)  Rated impulse voltage 0.8 kV (to EN 60730-1)  Control pollution degree 3 (in acc. with EN 60730-1)  Ambient temperature range +0 +50°C  Temperature of medium +5 +110°C in control ball valve -10°C with stem heating upon request  Non-operating temperature -40 +80°C  Ambient humidity range 95% r.H., non-condensating (to EN 60730-1)  Maintenance Maintenance-free  Dimensions See «Dimensions» on page 5		· · · · · · · · · · · · · · · · · · ·				
Safety Protection class Degree of protection IP54 in all mounting positions EMC CE according to 89/336/EEC Mode of operation Rated impulse voltage Ontrol pollution degree 3 (in acc. with EN 60730-1) Ambient temperature range +0 +50°C Temperature of medium +5 +110°C in control ball valve -10°C with stem heating upon request Non-operating temperature Ambient humidity range 95% r.H., non-condensating (to EN 60730-1) Maintenance Dimensions See «Dimensions» on page 5	Sound power level	Max. 35 dB (A)				
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Mode of operation  Type 1 (to EN 60730-1)  Rated impulse voltage  0.8 kV (to EN 60730-1)  Control pollution degree  3 (in acc. with EN 60730-1)  Ambient temperature range  +0 +50 °C  Temperature of medium  +5 +110 °C in control ball valve  -10 °C with stem heating upon request  Non-operating temperature  Ambient humidity range  95% r.H., non-condensating (to EN 60730-1)  Maintenance  Maintenance  Maintenance-free  Dimensions  See «Dimensions» on page 5		<u> </u>				
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Ambient humidity range 95% r.H., non-condensating (to EN 60730-1)  Maintenance Maintenance-free  Dimensions/weight  Dimensions See «Dimensions» on page 5						
Ambient humidity range 95% r.H., non-condensating (to EN 60730-1)  Maintenance Maintenance-free  Dimensions/weight  Dimensions See «Dimensions» on page 5	Non-operating temperature	<u> </u>				
Dimensions/weight Dimensions See «Dimensions» on page 5						
Dimensions See «Dimensions» on page 5	Maintenance					
	Dimensions/weight					
Weight Approx. 500 g	Dimensions	See «Dimensions» on page 5				
	Weight	Approx. 500 g				



### Safety notes



- The rotary actuator has been designed for use in stationary heating, ventilation and air conditioning systems and is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel.
   All applicable legal or institutional installation regulations must be complied with.
- The switch for changing the direction of rotation may only be operated by authorized personnel. The direction of rotation must not be reversed in a frost protection circuit.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · The cable is not allowed to be removed from the unit.
- The device contains electrical and electronic components and is not allowed to be disposed
  of as household refuse. All locally valid regulations and requirements must be observed.

### **Product features**

Mode of operation

Conventional operation: The actuator is controlled with a standard modulating signal of DC 0 ... 10 V and travels to the position defined by the control signal. Measuring voltage U serves for the electrical display of the actuator position 0 ... 100% and as slave control signal for other actuators.

*Operation on the MP-Bus:* The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and travels to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators

The factory settings cover the most common applications. Input and output signals and other parameters can be altered with the MFT-H parameterising device or the BELIMO Service Tool, MFT-P.

Simple direct mounting

Straightforward direct mounting on the ball valve with only one screw. The mounting position in relation to the ball valve can be selected in 90° < steps.

Manual override

Manual operation with pushbutton possible - temporary, permanently. The gear is disengaged and the actuator decoupled for as long as the button is pressed / latched.

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Home position

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the «gear disengagement» switch, the actuator travels to the home position. Factory setting: Direction of rotation Y2 (counter-clockwise rotation)

Rotary actuator	Rotary valve	
<b>√</b> Y2	A – AB = 0%	
Y1.	A – AB = 100%	

The actuator then moves into the position defined by the control signal.

### **Accessories**

**Electrical accessories** 

Description	Data sheet
Auxiliary switch SA	T2 - SA
Feedback potentiometer PA	T2 - PA
Parameterizing device MFT-H	T2 - MFT-H
PC-Tool MFT-P	T2 - MFT-P
Positioner SG24	T2 - SG24
Digital position indicator ZAD24	T2 - ZAD24



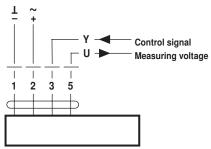
# **Electrical installation**

### Wiring diagram

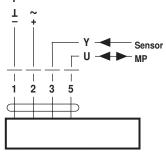
### Note

- Connect via safety isolation transformer.
- Parallel connection of other actuators possible.
- Direction of rotation switch is covered. Factory setting: Direction of rotation Y2

# **Conventional operation**

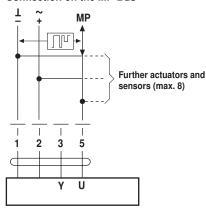


### Operation on the MP-Bus



# Functions when operated on MP-Bus

### Connection on the MP-Bus



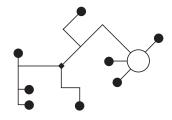
### Supply and communication

in one and the same 3-wire cable

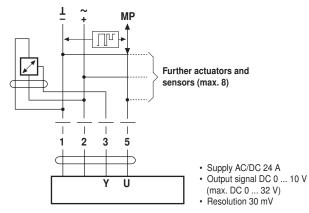
- · no shielding or twisting necessary
- · no terminating resistors required

#### Power topology

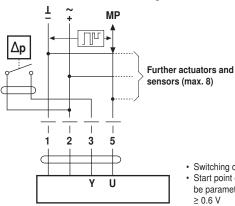
There are no restrictions for the network topology (star, ring, tree or hybrid forms are permitted).



### Connection of active sensors

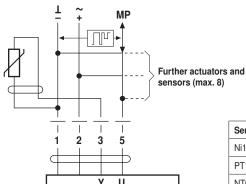


### Connection of external switching contact



- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as

### Connection of passive sensors

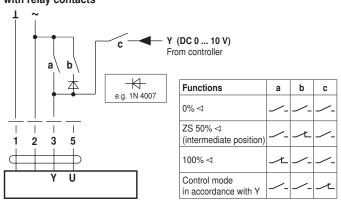


Sensor	Temperature range	Resistance range	Resolution
Ni1000	−28 +98°C	850 1600 Ω	1 Ω
PT1000	−35 +155°C	850 1600 Ω	1 Ω
NTC	-10 +160 °C (depending on type)	200 Ω 60 kΩ	1Ω

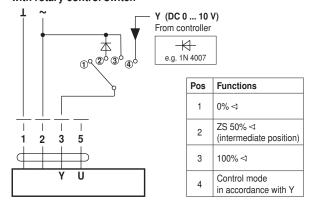


# Functions with basic values (only in conventional mode)

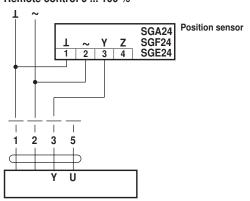
# Override control with AC 24 V with relay contacts



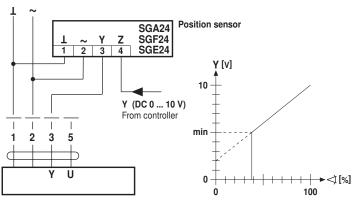
# Override control with AC 24 V with rotary control switch



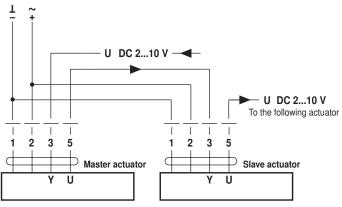
#### Remote control 0 ... 100 %



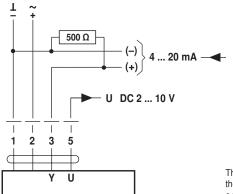
#### **Minimum limit**



### Master/Slave control (position-dependent)

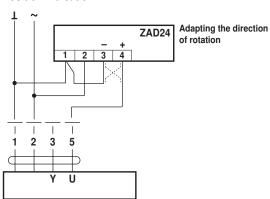


Control with 4 ... 20 mA via external resistance

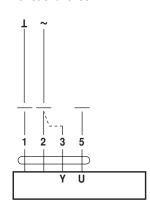


The 500  $\Omega$  resistor converts the 4 ... 20 mA current signal to a voltage signal DC 2 ... 10 V

### **Position indication**



### **Functional check**



### Procedure

- Apply AC 24 A to connection 1 and 2
- Disconnect connection 3:
  - For direction of rotation Y1:
     Actuator turns in the direction of \*
  - For direction of rotation Y2:
     Actuator turns in the direction of
- Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

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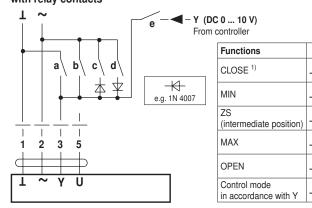
а

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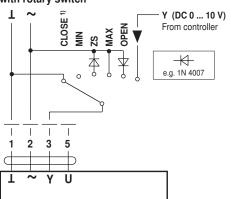


# Functions for actuators with specific parameters

### Override control and limiting with AC 24 V with relay contacts

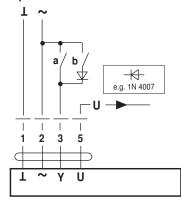


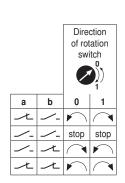
# Override control and limiting with AC 24 V with rotary switch

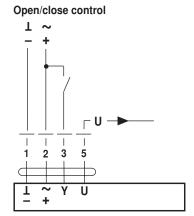


1) Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V.

### 3-point control

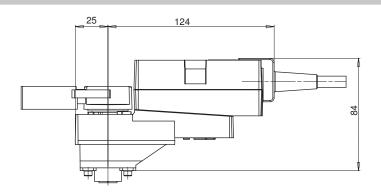


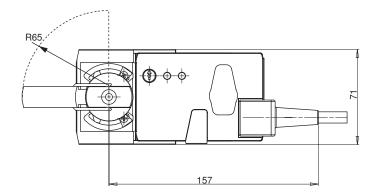




# Dimensions [mm]

### **Dimensional diagrams**







# Operating controls and indicators



1 Direction of rotation switch

Switching over: Direction of rotation changes

2 Pushbutton and green LED display

Off: No voltage supply or malfunction

Green on: Operation

Press button: Switches on angle of rotation adaption followed by standard operation

3 Pushbutton and yellow LED display

Off: Standard operation without MP-Bus
Yellow on: Adaption or synchronising process active
Yellow, blinking: Addressing request sent to MP master
Press button: Acknowledgment of addressing
Yellow, flickering: MP communication active

(4) Gear disengagement switch

Press button: Gear disengaged, motor stops, manual operation possible

Release button: Gear engaged, synchronisation starts, followed by standard operation

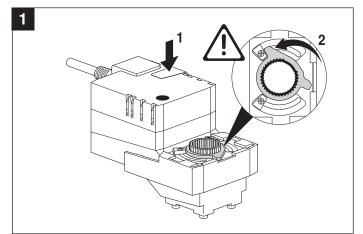
5 Service plug

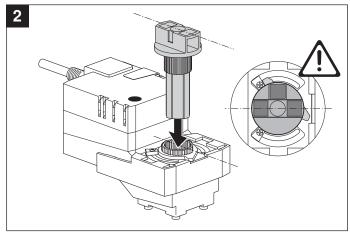
For connecting parameterising and service tools

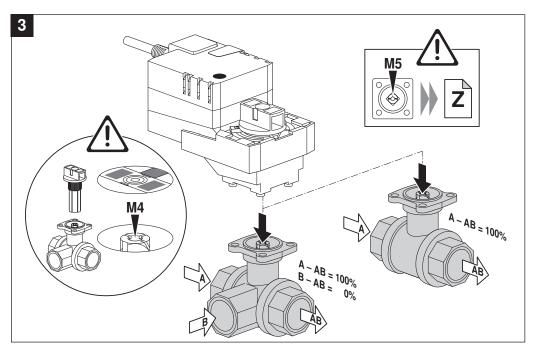
**Further documentations** 

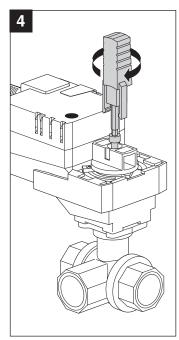
- · Complete overview of actuators for water solutions
- Data sheets for butterfly valves
- Installation instructions for actuators and/or ball valves
- Notes for project planning (hydraulic characteristic curves and circuits, installation regulations, commissioning, maintenance etc.)

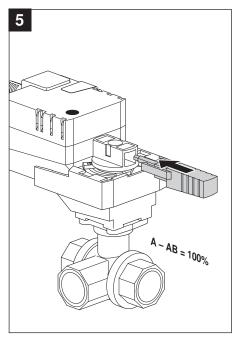


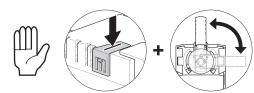


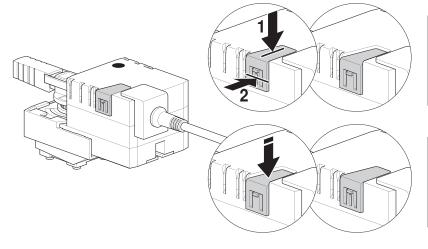




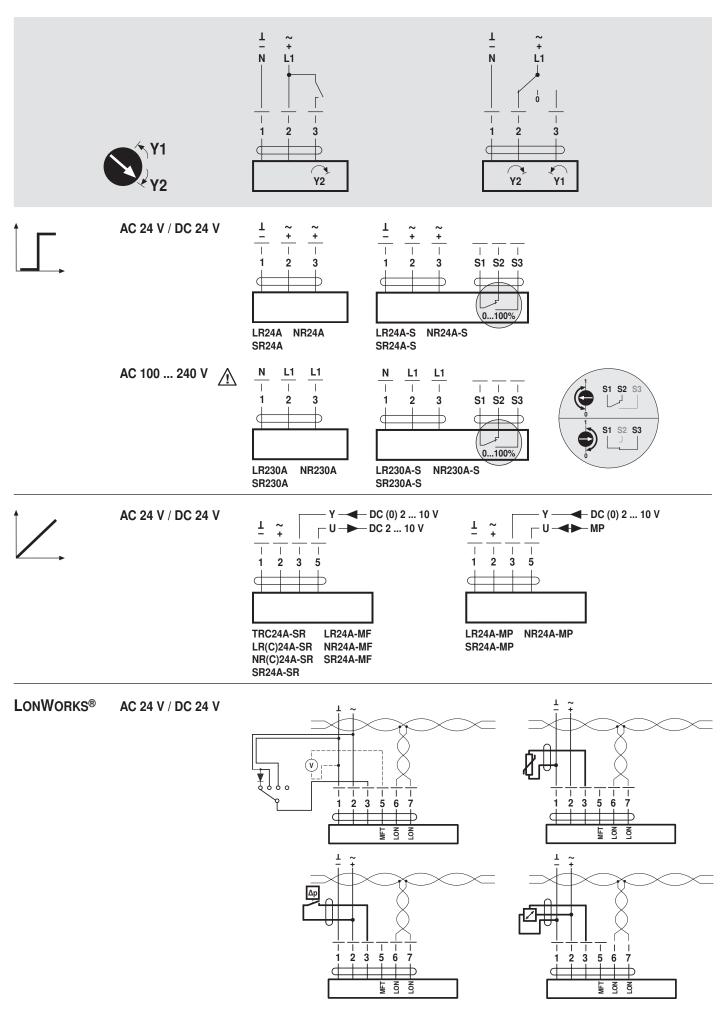














# TR..A.. / LR..A.. / NR..A.. / SR..A..







